

Introduction to Reinforcement Learning

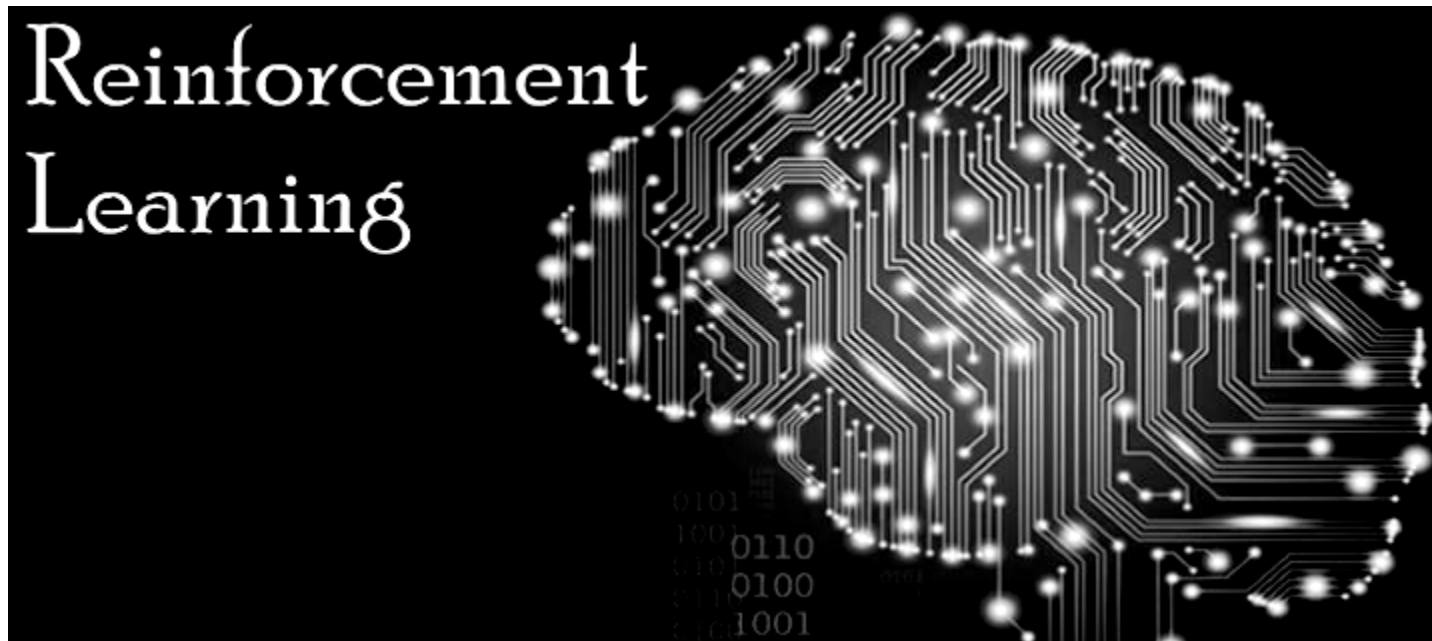
w/ some applications to Energy

LEC 1a: Course Organization

Instructors: Professor Scott Moura & Saehong Park

TA: Xinyi Zhao

Summer 2020



Why take this course?

*Obtain conceptual understanding of
reinforcement learning*

Why take this course? (details)

- Demystify reinforcement learning
- Obtain a solid foundation for the basic fundamental concepts
- Explore via an energy systems example
- It's only EIGHT days and 12 hours

This course is NOT about...

- Open source software
 - e.g. Google Deep Mind, OpenAI, TensorFlow, Matlab RL Toobox, Pytorch, etc.
- Reducing RL to coding
- Deep RL tricks
- Surveying the most famous algorithms of 2020
 - We take a long time horizon view about the past, present, and future

Prerequisite Previous Coursework

- Multivariable calculus
- Linear algebra
- Random variables & Probability
- Optimization
- Machine Learning
- Numerical computing

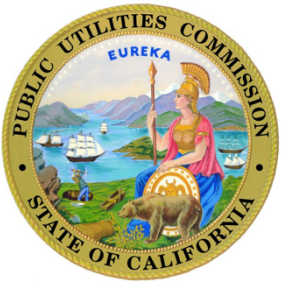
Very helpful (but not required) previous/concurrent coursework

- Dynamical Systems & Feedback Control
- Stochastic processes
- Statistical learning & Information Theory

Startups out of my courses



Selected Companies that recruit my students



 Exclusive access to alumni above! Join the CE295 LinkedIn Group: <https://www.linkedin.com/groups/7068321>

Class Format

Live Lecture Dates:

China Time: 7, 8, 9, 10 (Tu – Fri), 14, 15, 16, 17 (Tu – Fri); 08:30 – 10:05

Berkeley Time: 6, 7, 8, 9 (M– Th), 13, 14, 15, 16 (M – Th); 17:30 – 19:05

Remote Teaching: Zoom (detailed login info coming soon)

Course Website: <https://scott-moura.github.io/rl/>

Discussions: WeChat & Slack



Professor Scott MOURA

smoura@berkeley.edu

Office Hours:
30min after class



Co-instructor: Saehong Park

sspark@berkeley.edu

Office Hours: 30min after class



Teaching Assistant:

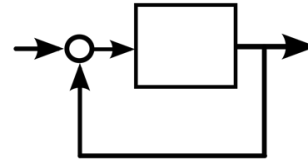
Xinyi Zhao

zxxyx48@163.com

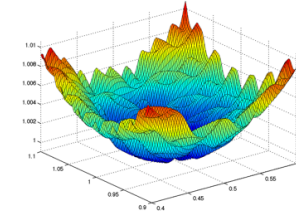
About me



FUNDAMENTAL
RESEARCH



Dynamic Systems
& Control

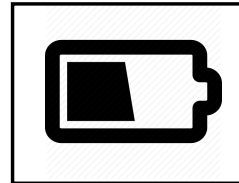


Optimization



Data Science

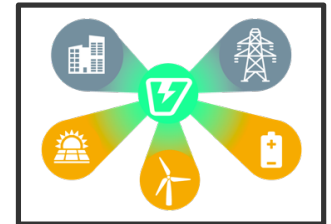
APPLICATIONS



Battery Management
Systems (#BATT)



Automated, Connected, &
Electric Vehicles (#ACES)



Distributed Energy
Resources (#DER)

Professor Scott Moura

Postdoc – UC San Diego

PhD MechE – University of Michigan

MS MechE – University of Michigan

BS MechE – UC Berkeley

Selected Honors

- Carol D. Soc Distinguished Grad Student Mentoring Award
- NSF CAREER Awardee
- Hugo O. Schuck Best Paper Award
- Best Student Paper, as advisor (ACC, IFAC, DSCC)
- UC President's Postdoctoral Fellow
- NSF Graduate Research Fellow



Dr. Luis COUTO
(ULB/Oxford)



Laurel
DUNN



Zach
GIMA



Saehong
PARK



Dong
ZHANG



Zhe
ZHOU



Sangjae
BAE



Bertrand
TRAVACCA



Mathilde
BADOUAL



Soomin
WOO



Yiqi
ZHAO



Ioanna
KAVVADA



Aaron
KANDEL



Patrick
KEYANTUO



Dylan
KATO



Teng
ZENG



Jing YU
(TBSI)



Shirin
YOUSEFIZADEH
(Aalborg, DK)



Andrea POZZI
(Pavia, IT)



Upadhi
VIJAY



Pedro
ERRAZURIZ



Sihan
LIU



Yan
XIAO



Jonathan
KESTELMAN



Deep
DAYARAMANI



Sonia
MARTIN




Vanessa
HERNANDEZ-CRUZ




German
PEREA

WeChat



 RL for Energy Systems-2020



该二维码7天内(6月26日前)有效, 重新进入将更新



This block contains a WeChat QR code for a group named "RL for Energy Systems-2020". At the top left, there is a small profile picture and the group name. The QR code is large and centered. At the bottom, there is a line of Chinese text: "该二维码7天内(6月26日前)有效, 重新进入将更新".


 **Scott Moura** 
Shenzhen, Guangdong



Scan the QR code to add me on WeChat

This block contains a WeChat QR code for a contact named "Scott Moura". At the top left, there is a profile picture, the name "Scott Moura" with a verified account icon, and the location "Shenzhen, Guangdong". The QR code is large and centered, with a smaller version of the profile picture overlaid on it. At the bottom, there is the text "Scan the QR code to add me on WeChat".

 **Saehong Park (박세홍,...** 



Scan the QR code to add me on WeChat

This block contains a WeChat QR code for a contact named "Saehong Park (박세홍,...)". At the top left, there is a profile picture, the name "Saehong Park (박세홍,...)", and a verified account icon. The QR code is large and centered, with a smaller version of the profile picture overlaid on it. At the bottom, there is the text "Scan the QR code to add me on WeChat".

Slack



Click to Join!

https://join.slack.com/t/introtorlucbtbsi/shared_invite/zt-flhuxmhu-rmGkBUOlpSxzI3d8I5F_yQ

Course Organization

Lectures

- Pre-recorded videos
- During lecture time, watch videos, pause, discuss

Notes

- Course notes available at <https://scott-moura.github.io/rl/>

Assignments

- Two assignments
- Application to Offshore Wind Energy

Topic Outline

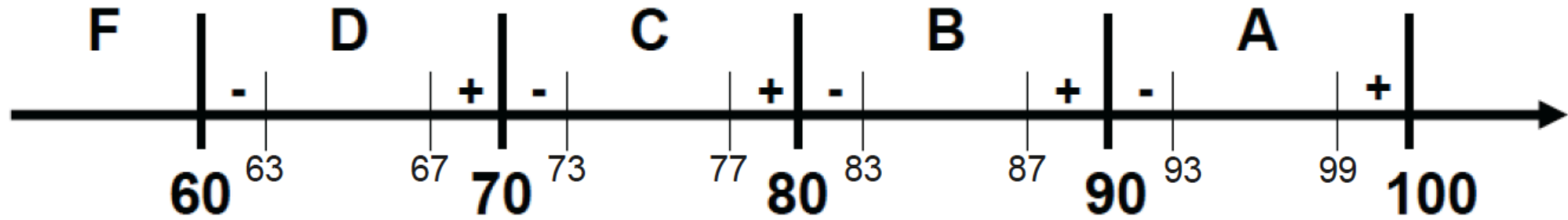
1. Optimal Control
2. Dynamic Programming
 1. Principal of Optimality & Value Functions
 - Case Study: Linear Quadratic Regulator (LQR)
3. Policy Iteration & Value Iteration
 - Case Study: LQR
4. Approximate Dynamic Programming (ADP)
 1. Temporal Difference (TD) Error
 2. Value Function Approximation
 - Case Study: LQR
 3. Online RL with ADP
 4. Actor-Critic Method
 - Case Study: Offshore Wind
5. Q-Learning
 1. Q-learning algorithm
 2. Advanced Q-learning algorithm, i.e., DQN
6. Policy Gradient
 1. Vanilla policy gradient (REINFORCE)
7. Actor-Critic using Policy Gradient
 1. Actor-Critic using Policy Gradient
 2. Advanced Actor-Critic algorithm, i.e., DDPG
8. RL for energy systems
 1. Case Study: Battery Fast-charging

Textbooks (none are required)

The following are recommended for additional background:

1. D. P. Bertsekas and J. Tsitsiklis, Neuro-Dynamic Programming, Athena Scientific, 1996
2. Powell, W. B. (2007). Approximate Dynamic Programming: Solving the curses of dimensionality (Vol. 703). John Wiley & Sons.
3. R. S. Sutton and A. G. Barto, Reinforcement Learning: An Introduction, 2017
4. Lewis, F., & Vrabie, D. (2009). Reinforcement learning and adaptive dynamic programming for feedback control. *IEEE Circuits and Systems Magazine*, 9(3), 32–50.
<http://doi.org/10.1109/MCAS.2009.933854>
5. Lewis, F. L., & Vrabie, D. (2009). Reinforcement learning and adaptive dynamic programming for feedback control. *IEEE Circuits and Systems Magazine*, 9(3), 32–50.
<http://doi.org/10.1109/MCAS.2009.933854>
6. J. Si, A. Barto, W. Powell D. Wunsch (2004). [Handbook of Learning and Approximate Dynamic Programming](#).

Grading



Straight scale (we may curve up, but it has never been necessary)

Participation	50pts	Based on attendance and interaction. Award at instructor's discretion
Assignments	50pts	Two assignments, 25pts each
TOTAL	100pts	

How to Succeed (in Remote Learning Courses)

- Ask questions in class! MORE important in remote learning
 - LIVE discussion
 - See instructors during office hours
 - Be resourceful!
 - Send us a WeChat/Slack.
-
- You are not alone!
 - Work together! Lift each other! Succeed Together!
 - You are responsible for making a better world for yourself & all