

# IV Example: LQR

Last time: ① TD error  
② Value  
For approx.

We have established:

- $V(x_k) = x_k^T P x_k$  is quadratic
- $u_k = K \cdot x_k$  is linear

Construct TD error:  $e_k = c + \gamma \cdot V_{\pi}(x_{k+1}) - V_{\pi}(x_k)$

$$e_k = x_k^T Q x_k + u_k^T R u_k + x_{k+1}^T P x_{k+1} - x_k^T P x_k$$

Note this is linear in parameter matrix  $P$ . basis vec

Next, let's re-write  $V(x_k) = x_k^T P x_k = \underbrace{W^T}_{\text{weights}} \phi(x)$

Define  $W = \text{vec}(P) \leftarrow$  stacks columns of  $P$  into  
one big column vector

$\phi(x) = x_k \otimes x_k \leftarrow$  is a vector of monomials  
of  $x_k$ .

For example:

$$x_k = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad P = \begin{bmatrix} p_{11} & p_{12} \\ * & p_{22} \end{bmatrix}$$

then 
$$x_k^T P x_k = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} p_{11} & p_{12} \\ * & p_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
$$= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} p_{11}x_1 + p_{12}x_2 \\ p_{12}x_1 + p_{22}x_2 \end{bmatrix}$$

$$\begin{aligned}
 V &= \underline{P_{11}} x_1^2 + \underline{P_{12}} x_2 x_1 + \underline{P_{12}} x_1 x_2 + \underline{P_{22}} x_2^2 \\
 &= \underbrace{[P_{11} \quad 2P_{12} \quad P_{22}]}_{= W^T} \underbrace{\begin{bmatrix} x_1^2 \\ x_1 x_2 \\ x_2^2 \end{bmatrix}}_{= \phi(x)} = W^T \phi(x)
 \end{aligned}$$

Note  $P$  is symmetric, we have  
 $\phi(x): \mathbb{R}^n \rightarrow \mathbb{R}^{n(n+1)/2}$ .

We can re-write the TD error as:

$$e_k = \underbrace{x_k^T Q x_k + u_k^T R u_k}_{c(x_k, u_k)} + W^T \phi(x_{k+1}) - W^T \phi(x_k)$$

$$= c(x_k, u_k) + W^T [\phi(x_{k+1}) - \phi(x_k)]$$

The TD error can be computed for supervised learning of  $V_{\pi}(\cdot)$  by collecting  $(x_k, x_{k+1}, c(x_k, u_k))$  at each time step

Remark: Previously, DP algos required eval of Bellman eqn at all  $x_k \in X$ . To achieve this computationally, we considered a discrete-value state space  $X$ . This results in an exponential increase in calculations as the state vector size increases, known as "curse of dimensionality."

Value fn approx bypasses the curse of dimensionality!